

Modelling of poroelastic carpets

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Mini-Symposium on Flows over Non-Smooth Walls

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Man often tries to achieve technical surfaces which are rigid and smooth...



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... but in Nature, porous, anisotropic, irregular, elastic, rough is the norm!



Motivation

In biomimetics we deal with several separation of scales phenomena



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Motivation

In biomimetics we deal with several separation of scales phenomena







- Theory of homogenization applied to poroelastic media
- Resolution of the microscopic equations
 - Permeability tensor
 - Elasticity tensor
- Resolution of the macroscopic equations
 - Oscillating channel flow
- Left to do ...

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Introduction: carpet of elastic fibres



Transversely isotropic porous medium, made by fibers shown in the (x_1, x_3) and (x_1, x_2) plane, respectively. The dotted rectangle in the two frames represents the elementary cell V. V_f is the volume occupied by the fluid and V_s is that occupied by the solid, so that $V = V_f + V_s$. Γ is the fluid-solid microscopic interface. The porosity ϑ is defined as V_f/V . All the unknowns are periodic over V.

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Introduction: carpet of elastic fibres





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The scales considered

$$U = \frac{V}{T_S} \qquad \text{No slip on } \Gamma$$

$$E \frac{Pl^2}{\mu L^2} T_S = P, \qquad \text{macroscopic solid stresses balanced by pressure on } \Gamma$$

$$\frac{P}{L} = \frac{\mu U}{l^2} \qquad \text{macroscopic press forces balanced by viscous dissipation}$$

$$\Rightarrow T_S = \frac{\mu L^2}{El^2} = \frac{\mu}{\epsilon^2 E} \qquad \text{solid time scale}$$

$$\frac{\rho_s}{T_S^2} = \frac{E}{L^2}, \qquad \text{inertia of the solid of the same order of the solid stress}$$

(Fluid and solid variables)

$$\hat{\mathbf{x}} = l\mathbf{x}, \quad \hat{p} = Pp, \quad \hat{t}_f = \frac{lt_f}{U}, \quad \hat{\mathbf{u}} = \epsilon \frac{Pl}{\mu} \mathbf{u}$$
$$\hat{\mathbf{v}} = \frac{PL}{E} \mathbf{v}, \quad \hat{t}_s = \frac{\mu t_s}{E\epsilon^2}$$

The homogenized model

$$\frac{\partial u_i}{\partial x_i} = 0 \text{ on } V_f$$

$$\epsilon \operatorname{Re}_I \left(\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} \right) = -\frac{\partial p}{\partial x_i} + \epsilon \nabla^2 u_i \text{ on } V_f$$

$$\epsilon^2 \frac{\partial^2 v_i}{\partial t_s^2} = \frac{\partial}{\partial x_i} C_{ijkl} \varepsilon_{kl}(\mathbf{v}) \text{ on } V_s$$

linked by

$$u_{i} = \frac{\partial v_{i}}{\partial t} \text{ and } -p n_{i} + 2\epsilon \varepsilon_{ij}(\mathbf{u})n_{j} = \frac{1}{\epsilon} \left[C_{ijkl} \varepsilon_{kl}(\mathbf{v}) \right] n_{j} \text{ on } \Gamma$$
$$\operatorname{Re}_{l} = \frac{\rho_{f} U l}{\mu} = \epsilon \frac{\rho_{f} U L}{\mu} = \epsilon \operatorname{Re}_{L}$$

DEVELOPED MODELS

• $\operatorname{Re}_{l} = \mathcal{O}(\epsilon)$ & $\mathcal{O}(1)$ for poroelastic media, isotropic and anisotropic

$$egin{aligned} &\left(1-artheta
ight)rac{\partial^2 v_i^{(0)}}{\partial t^2} = rac{\partial}{\partial x_j'}\left[\mathcal{C}_{ijpq}arepsilon_{pq}'(\mathbf{v}^{(0)}) - lpha_{ij}'p^{(0)}
ight] \ & \left(rac{\partial\langle u_i^{(0)}
angle}{\partial x_i'} = \langlerac{\partial\chi_i^{pq}}{\partial x_i}
anglearepsilon_{pq}'(\dot{\mathbf{v}}^{(0)}) - \langlerac{\partial\eta_i}{\partial x_i}
angle\dot{p}^{(0)} \ & \langle u_i^{(0)}
angle - artheta\dot{v}_i^{(0)} = -\mathcal{K}_{ij}rac{\partial p^{(0)}}{\partial x_i'} \end{aligned}$$

valid in the homogenized macroscopic domain, and the equations for the microscopic fields χ , η , K and A valid in the microcell

$$\begin{cases} \frac{\partial}{\partial x_j} \left\{ C_{ijkl} \left[\varepsilon_{kl}(\chi^{pq}) + \delta_{kp} \delta_{lq} \right] \right\} = 0, \\ \left\{ C_{ijkl} \left[\varepsilon_{kl}(\chi^{pq}) + \delta_{kp} \delta_{lq} \right] \right\} n_j = 0 \quad \text{on } \Gamma \\ \begin{cases} \frac{\partial}{\partial x_j} \left[C_{ijkl} \varepsilon_{kl}(\eta) \right] = 0, \\ \left[C_{ijkl} \varepsilon_{kl}(\eta) \right] n_j = -n_i \quad \text{on } \Gamma \end{cases} \begin{cases} \frac{\partial A_j}{\partial x_i} - \frac{\partial^2 K_{ij}}{\partial x_k^2} = \delta_{ij}, \\ \frac{\partial K_{ij}}{\partial x_i} = 0, \\ K_{ii}(\mathbf{x}, t) = 0 \quad \text{on } \Gamma \end{cases} \end{cases}$$

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$$\begin{cases} (1-\vartheta)\frac{\partial^2 v_i^{(0)}}{\partial t^2} = \frac{\partial}{\partial x'_j} \left[\begin{array}{c} \mathcal{C}_{ijpq} \varepsilon'_{pq}(\mathbf{v}^{(0)}) - \alpha'_{ij}p^{(0)} \right] \\ \\ \frac{\partial \langle u_i^{(0)} \rangle}{\partial x'_i} = \left\langle \frac{\partial \chi_i^{pq}}{\partial x_i} \right\rangle \varepsilon'_{pq}(\dot{\mathbf{v}}^{(0)}) - \langle \frac{\partial \eta_i}{\partial x_i} \rangle \dot{p}^{(0)} \\ \\ \langle u_i^{(0)} \rangle - \vartheta \dot{\mathbf{v}}_i^{(0)} = -\mathcal{K}_{ij} \frac{\partial p^{(0)}}{\partial x'_i} \end{cases}$$

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$$\begin{cases} (1-\vartheta)\frac{\partial^2 v_i^{(0)}}{\partial t^2} + \left[\operatorname{Re}_I U_j \langle \frac{\partial u_i^{(0)}}{\partial x_j} \rangle \right] = \frac{\partial}{\partial x_j'} \left[\mathcal{C}_{ijpq} \varepsilon_{pq}'(\mathbf{v}^{(0)}) - \alpha_{ij}' p^{(0)} \right] \\ \\ \frac{\partial \langle u_i^{(0)} \rangle}{\partial x_i'} = \left\langle \frac{\partial \chi_i^{pq}}{\partial x_i} \right\rangle \varepsilon_{pq}'(\mathbf{v}^{(0)}) - \left\langle \frac{\partial \eta_i}{\partial x_i} \right\rangle \dot{p}^{(0)} \\ \\ \langle u_i^{(0)} \rangle - \vartheta \dot{v}_i^{(0)} = - \left[\mathcal{K}_{ij} \right] \frac{\partial p^{(0)}}{\partial x_j'} \end{cases}$$

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$$\begin{cases} \boxed{\operatorname{Re}_{l}U_{k}\frac{\partial K_{ij}}{\partial x_{k}}} = -\frac{\partial A_{j}}{\partial x_{i}} + \frac{\partial^{2}K_{ij}}{\partial x_{k}^{2}} + \delta_{ij}, \\ \frac{\partial K_{ij}}{\partial x_{i}} = 0, \\ K_{ij}(\mathbf{x}, t) = 0 \quad \text{on } \Gamma \end{cases}$$

$\operatorname{Re}_{l} = \mathcal{O}(\epsilon)$: packed rigid spheres



$$\mathcal{K}_{ij} = \mathcal{K}\delta_{ij}$$



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$\operatorname{Re}_{l} = \mathcal{O}(\epsilon)$: packed rigid spheres



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$\operatorname{Re}_{l} = \mathcal{O}(\epsilon)$: arrays of rigid cylinders



$$\mathcal{K}_{11} = \mathcal{K}_{22}$$



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$\operatorname{Re}_{l} = \mathcal{O}(\epsilon)$: arrays of rigid cylinders



 \mathcal{K}_{33}

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$\operatorname{Re}_{l} = \mathcal{O}(\epsilon)$: arrays of rigid cylinders



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 ${\sf Re}_l = \mathcal{O}(1)$

Macroscopic level

$$\begin{cases} (1-\vartheta)\frac{\partial^2 v_i^{(0)}}{\partial t^2} + Re_l U_j \langle \frac{\partial u_i^{(0)}}{\partial x_j} \rangle = \frac{\partial}{\partial x_j'} \left[\mathcal{C}_{ijpq} \varepsilon_{pq}'(\mathbf{v}^{(0)}) - \alpha_{ij}' p^{(0)} \right] \\ \frac{\partial \langle u_i^{(0)} \rangle}{\partial x_i'} = \langle \frac{\partial \chi_i^{pq}}{\partial x_i} \rangle \varepsilon_{pq}'(\mathbf{\dot{v}}^{(0)}) - \langle \frac{\partial \eta_i}{\partial x_i} \rangle \dot{p}^{(0)} \\ \langle u_i^{(0)} \rangle - \vartheta \dot{v}_i^{(0)} = -\mathcal{K}_{ij} \frac{\partial p^{(0)}}{\partial x_j'} \end{cases}$$

Microscopic level

$$egin{aligned} & \mathcal{R}e_{l}\mathcal{U}_{k}rac{\partial\mathcal{K}_{ij}}{\partial x_{k}}\simeq-rac{\partial\mathcal{A}_{j}}{\partial x_{i}}+rac{\partial^{2}\mathcal{K}_{ij}}{\partial x_{k}^{2}}+\delta_{ij}, & rac{\partial\mathcal{K}_{ij}}{\partial x_{i}}=0 \ & \mathcal{K}_{ij}(\mathbf{x},t)=0 \quad on \ \Gamma, \quad plus \ periodicity \ over \ V_{f} \ & \mathcal{R}e_{l}=rac{\mathcal{U}l}{
u}, \quad \mathcal{U}_{k}:=rac{1}{\mathcal{V}_{Tot}}\int_{V_{Tot}}\langle u_{k}^{(0)}
angle \, dV \end{aligned}$$

MICRO and MACRO level linked by iterations over U_k .

cf. Gustaffson & Protas (2013) on the use of Oseen's closure for high Re

$\operatorname{\mathsf{Re}}_{l}U_{k}\in[0,150]\delta_{1k}$, artheta=0.7



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Edwards et al. (1990)



$$\mathsf{Re}_l = \mathcal{O}(1)
ightarrow \mathcal{K}_{ij} = \ egin{pmatrix} \mathscr{O}(10^{-9}) & \mathcal{O}(10^{-9}) \ \mathcal{O}(10^{-9}) & \mathscr{O}(10^{-9}) \ \mathcal{O}(10^{-9}) & \mathcal{O}(10^{-9}) & \mathscr{O}(10^{-9}) \ \end{pmatrix}$$

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$\operatorname{Re}_{I}U_{k}=(c,0,0)$

Ghisalberti & Nepf (2004,2006,2009)



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$\operatorname{Re}_{I}U_{k} = (10, 20, 15), \ \vartheta = 0.7$



$\operatorname{Re}_{I}U_{k} = (10, 20, 15), \ \vartheta = 0.7$



$$\begin{cases} (1-\vartheta)\frac{\partial^2 v_i^{(0)}}{\partial t^2} = \frac{\partial}{\partial x_j'} \left[\begin{array}{c} \mathcal{C}_{ijpq} \\ \mathcal{C}_{ijpq} \end{array} \varepsilon_{pq}'(\mathbf{v}^{(0)}) - \begin{array}{c} \alpha_{ij}' \\ \alpha_{ij}' \end{array} p^{(0)} \right] \\ \frac{\partial \langle u_i^{(0)} \rangle}{\partial x_i'} = \left\langle \frac{\partial \chi_i^{pq}}{\partial x_i} \right\rangle \varepsilon_{pq}'(\dot{\mathbf{v}}^{(0)}) - \left\langle \frac{\partial \eta_i}{\partial x_i} \right\rangle \dot{p}^{(0)} \\ \langle u_i^{(0)} \rangle - \vartheta \dot{\mathbf{v}}_i^{(0)} = - \begin{array}{c} \mathcal{K}_{ij} \\ \frac{\partial p^{(0)}}{\partial x_i'} \end{array} \end{cases}$$

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$\operatorname{Re}_{l} = O(\epsilon) \& \operatorname{Re}_{l} = O(1)$ effective tensors

(Cylinders, $\vartheta = 0.3 - 0.99$)

$$\begin{cases} \frac{\partial}{\partial x_j} \left\{ C_{ijkl} \left[\varepsilon_{kl} (\chi^{pq}) + \delta_{kp} \delta_{lq} \right] \right\} = 0, \\ \left\{ C_{ijkl} \left[\varepsilon_{kl} (\chi^{pq}) + \delta_{kp} \delta_{lq} \right] \right\} n_j = 0 \quad \text{on } \Gamma, \end{cases}$$

$$C_{ijpq} = \langle C_{ijkl} \ \varepsilon_{kl}(\chi^{pq}) \rangle + \langle C_{ijpq} \rangle = \begin{pmatrix} \bigcirc & \blacksquare & \bigotimes & 0 & 0 & 0 \\ & \bigcirc & \bigotimes & 0 & 0 & 0 \\ \otimes & \bigotimes & \bigstar & 0 & 0 & 0 \\ 0 & 0 & 0 & \bigstar & 0 & 0 \\ 0 & 0 & 0 & 0 & \bigstar & 0 \\ 0 & 0 & 0 & 0 & \bigstar & 0 \end{pmatrix}$$

$\operatorname{Re}_{l} = O(\epsilon) \& \operatorname{Re}_{l} = O(1)$ effective tensors

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$\operatorname{Re}_{l} = O(\epsilon)$ & $\operatorname{Re}_{l} = O(1)$ effective tensors

(Linked cylinders, $\vartheta \approx 0.8$)

$$\begin{cases} \frac{\partial}{\partial x_j} \left\{ C_{ijkl} \left[\varepsilon_{kl} (\chi^{pq}) + \delta_{kp} \delta_{lq} \right] \right\} = 0, \\ \left\{ C_{ijkl} \left[\varepsilon_{kl} (\chi^{pq}) + \delta_{kp} \delta_{lq} \right] \right\} n_j = 0 \quad \text{on } \Gamma, \end{cases}$$

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 $\operatorname{Re}_{l} = O(\epsilon) \& \operatorname{Re}_{l} = O(1)$ effective tensors

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Averaged components of the effective elasticity tensors



Macroscopic simulations: oscillating channel flow

A domain-decomposition-based solver



Macroscopic results: linked cylinders

$$\begin{cases} (1-\vartheta)\frac{\partial^2 v_i^{(0)}}{\partial t^2} = \frac{\partial}{\partial x_j'} \left[\mathcal{C}_{ijpq} \varepsilon_{pq}'(\mathbf{v}^{(0)}) - \alpha_{ij}' p^{(0)} \right] \\ \frac{\partial \langle u_i^{(0)} \rangle}{\partial x_i'} = \langle \frac{\partial \chi_i^{pq}}{\partial x_i} \rangle \varepsilon_{pq}'(\dot{\mathbf{v}}^{(0)}) - \langle \frac{\partial \eta_i}{\partial x_i} \rangle \dot{p}^{(0)} \\ \langle u_i^{(0)} \rangle - \vartheta \dot{v}_i^{(0)} = -\mathcal{K}_{ij} \frac{\partial p^{(0)}}{\partial x_i'} \end{cases}$$

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NSE are forced by an oscillating pressure gradient of the form $\Re(Ae^{i\omega t}).$ Solution shown for

- $\rho_f = 1.22 \ kg/m^3$, air,
- Re_L = 100,
- Ca = 9.15×10^{-8} (polyurethane foam, $E = 3 \times 10^{5}$ Pa, $\nu_{P} = 0.39$),
- $A = \omega = 1$.



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- $A = \omega = 1$.

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NSE are forced by an oscillating pressure gradient of the form $\Re(Ae^{i\omega t}).$ Solution shown for

•
$$\rho_f = 1.22 \ kg/m^3$$
, air,

- $Re_L = 100$,
- Ca = 9.15×10^{-8} (polyurethane foam, $E = 3 \times 10^{5}$ Pa, $\nu_{P} = 0.39$),
- $A = \omega = 1$.

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Left to do ...

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Considering higher order approximation (in $\epsilon = \frac{l}{L}$), $\langle u_i \rangle = \langle u_i^{(0)} \rangle + \epsilon \langle u_i^{(1)} \rangle$ and $\langle p \rangle = \langle p^{(0)} \rangle + \epsilon \langle p^{(1)} \rangle$:

Macroscopic level

$$\langle u_i^{(1)} \rangle = -\mathcal{L}_{ijk} \frac{\partial p^{(0)}}{\partial x_j'} \frac{\partial p^{(0)}}{\partial x_k'} - \mathcal{M}_{ijk} \frac{\partial^2 p^{(0)}}{\partial x_j' \partial x_k'} - \mathcal{K}_{ij} \frac{\partial p_0^{(1)}}{\partial x_j'}$$

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$\epsilon < {\sf Re} < 1$

Microscopic level

$$\begin{cases} \frac{\partial L_{ijk}}{\partial x_i} = 0 \\ \frac{\partial B_{jk}}{\partial x_i} - \frac{\partial L_{ijk}}{\partial x_g \partial x_g} = K_{lj} \frac{\partial K_{ik}}{\partial x_i} \begin{cases} \frac{\partial M_{ijk}}{\partial x_i} = -K_{kj} \\ \frac{\partial C_{jk}}{\partial x_i} - \frac{\partial M_{ijk}}{\partial x_g \partial x_g} = -A_j \delta_{ik} + 2 \frac{\partial K_{ij}}{\partial x_k} \end{cases} \\ L_{ijk} = S_{ij} = T_j = 0, \ M_{ijk} = -\frac{V}{|\Gamma|} \langle K_{kj} \rangle n_i \quad on \ \Gamma, \\ L_{ijk}, \ M_{ijk}, \ B_{jk}, \ C_{jk}, \ S_{ij}, \ T_j \ V\text{-periodic} \end{cases}$$



$$\langle L_{ijk} \rangle = 0$$

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Nield and Bejan (2006), Skjetne and Auriault (1999)

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Macroscopic simulations: the homogenized model

$$(\sigma_{ij}n_j)n_i|_{NS} = (\sigma_{ij}n_j)n_i|_{BR} \qquad (\sigma_{ij}n_j)t_i|_{NS} = (\sigma_{ij}n_j)t_i|_{BR}$$

can be written as

$$\left. \left(\frac{\partial u_1}{\partial x_3} + \frac{\partial u_3}{\partial x_1} \right) \right|_{NSE} = \left. \frac{\mu_e}{\mu} \left(\frac{\partial u_1}{\partial x_3} + \frac{\partial u_3}{\partial x_1} \right) \right|_{BRINK}$$

and

$$\left(-p + \frac{1}{2\text{Re}}\frac{\partial u_3}{\partial x_3}\right)\Big|_{NSE} = \left.\left(-p + \frac{\mu_e}{2\mu\text{Re}}\frac{\partial u_3}{\partial x_3}\right)\right|_{BRINK}$$

Macroscopic simulations: the homogenized model

Case 1
Case 2
Case 2

$$\langle u_i^{(0)} \rangle = -\mathcal{K}_{ij} \epsilon^2 \operatorname{Re}_L \frac{\partial p^{(0)}}{\partial x'_j} \qquad \langle u_i^{(0)} \rangle = -\mathcal{K}_{ij} \epsilon^2 \operatorname{Re}_L \frac{\partial p^{(0)}}{\partial x'_j} + \\
+\mathcal{K}_{ij} \epsilon^2 \frac{\mu_e}{\mu} \nabla^2 \langle u_j^{(0)} \rangle \\
u_i|_{NS} = u_i^{(0)}|_{DARCY} \qquad (\sigma_{ij} n_j) n_i|_{NS} = (\sigma_{ij} n_j) n_i|_{BR} \\
(\sigma_{ij} n_j) t_i|_{NS} = (\sigma_{ij} n_j) t_i|_{BR} \\
\delta = c \sqrt{\frac{\mathcal{K}}{\theta}} \qquad u_i|_{NS} = u_i^{(0)}|_{BR} \\
\text{Le Bars & Worster (2006).} \qquad \text{imposed at } y_{ITF}. \end{cases}$$

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Macroscopic simulations: Re_L=100



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