

Erratum to: Preliminary design of a small-sized flapping UAV: I. Aerodynamic performance and static longitudinal stability

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It has come to the attention of the authors that the aforementioned paper contains a typing error in Equation 3. Instead of reading

$$roll_{ew} = -\frac{A_{ie} \frac{\pi}{2} erf(\sqrt{2}\sqrt{B}cos(\omega t))}{2\sqrt{BC}},$$

Equation 3 should read:

$$roll_{ew} = -\frac{A_{ie} \sqrt{\frac{\pi}{2}} erf(\sqrt{2}\sqrt{B}cos(\omega t))}{2\sqrt{BC}}.$$

The online version of the original article can be found under doi:[10.1007/s11012-015-0298-6](https://doi.org/10.1007/s11012-015-0298-6).

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