

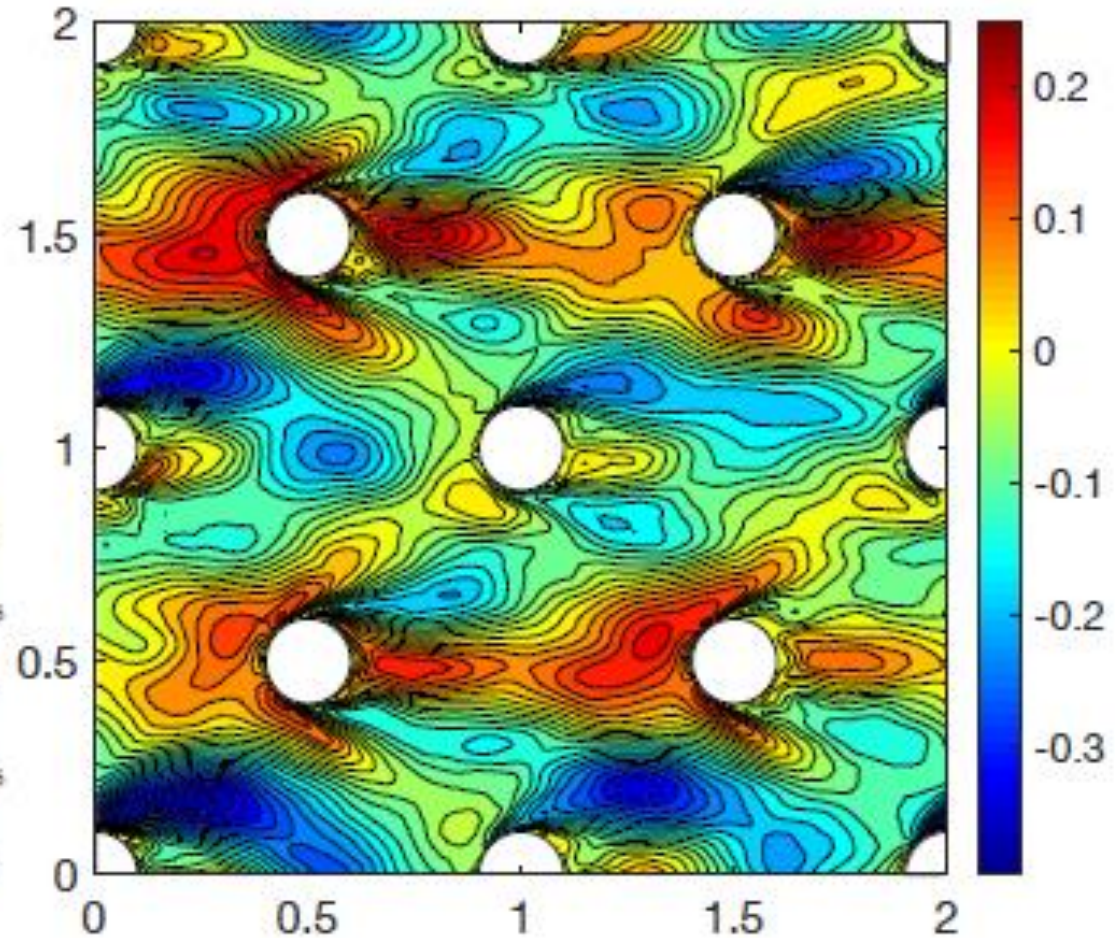
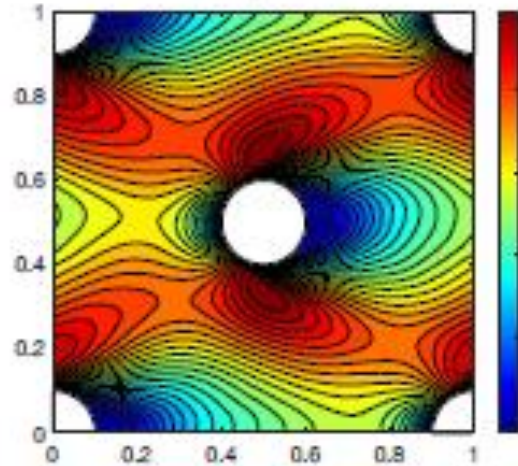
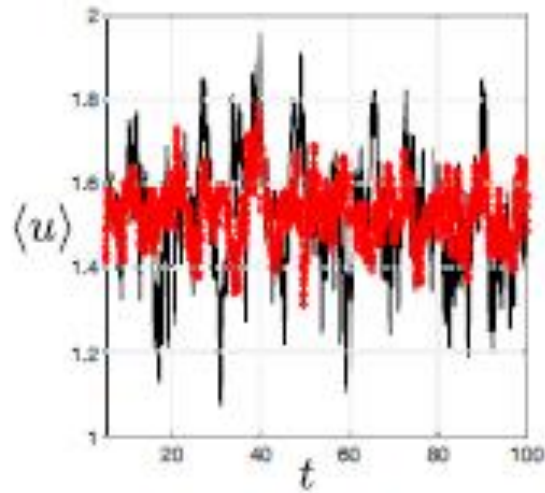
ADJOINT HOMOGENIZATION

Alessandro Bottaro



UNIVERSITÀ DEGLI STUDI
DI GENOVA

1. Porous media



$$\frac{\Delta P}{L} = \mathcal{O}\left(\frac{\mu \underline{u}}{l^2}\right)$$

$$\left\{ \begin{array}{l} \frac{\partial u_i}{\partial x_i} = 0, \\ Re \left[\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} \right] = -\frac{1}{\epsilon} \frac{\partial p}{\partial x_i} + \frac{\partial^2 u_i}{\partial x_j^2} + f_i \\ \epsilon = l/L \ll 1 \quad Re = \frac{\rho \underline{u} l}{\mu} \end{array} \right.$$

$$\frac{\partial}{\partial x_i} \rightarrow \frac{\partial}{\partial x_i} + \epsilon \frac{\partial}{\partial X_i}$$

$$g(t, x_i, X_i) = g^{(0)}(t, x_i, X_i) + \epsilon g^{(1)}(t, x_i, X_i) + \dots$$

$$\frac{\partial u_i^{(0)}}{\partial x_i} = 0,$$

$$\frac{\partial u_i^{(1)}}{\partial x_i} + \frac{\partial u_i^{(0)}}{\partial X_i} = 0,$$

$$\frac{\partial p^{(0)}}{\partial x_i} = 0,$$



$$p^{(0)} = p^{(0)}(t, X_i)$$

$$Re \left[\frac{\partial u_i^{(0)}}{\partial t} + u_j^{(0)} \frac{\partial u_i^{(0)}}{\partial x_j} \right] = -\frac{\partial p^{(1)}}{\partial x_i} - \frac{\partial p^{(0)}}{\partial X_i} + \frac{\partial^2 u_i^{(0)}}{\partial x_j^2} + \cancel{f_i^{(0)}}$$

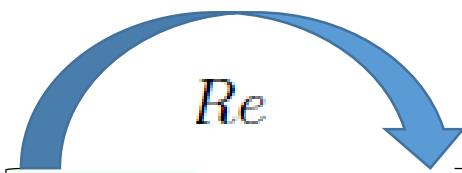
$$\langle a \rangle = \frac{1}{\mathcal{V}} \int_{\mathcal{V}_f} a \, d\mathcal{V},$$

$$(b, c) = \frac{1}{\mathcal{V}} \int_{\mathcal{V}_f} b c \, d\mathcal{V},$$

Lagrange-Green identity

$$\int_{\mathcal{V}} a \frac{\partial b}{\partial x_i} d\mathcal{V} = \int_{\partial\mathcal{V}} a b n_i dA - \int_{\mathcal{V}} \frac{\partial a}{\partial x_i} b d\mathcal{V}$$

$$0 = \int_0^T \int_{V_f} u_i^\dagger \left[- \frac{\partial u_i^{(0)}}{\partial t} + u_j^{(0)} \frac{\partial u_i^{(0)}}{\partial x_j} - \frac{\partial p^{(1)}}{\partial x_i} - \frac{\partial p^{(0)}}{\partial X_i} + \mu \frac{\partial^2 u_i^{(0)}}{\partial x_j^2} \right] + p_k^\dagger \frac{\partial u_i^{(0)}}{\partial x_i} dV dt$$



$$\begin{aligned}
& \int_0^T \left(\frac{\partial u_i^\dagger}{\partial x_i}, p^{(1)} \right) + \left(\operatorname{Re} \left[\frac{\partial u_i^\dagger}{\partial t} + u_j^{(0)} \frac{\partial u_i^\dagger}{\partial x_j} \right] - \frac{\partial p^\dagger}{\partial x_i} + \frac{\partial^2 u_i^\dagger}{\partial x_j^2}, u_i^{(0)} \right) dt \\
& = \int_0^T \left(u_i^\dagger, \frac{\partial p^{(0)}}{\partial X_i} - \cancel{f_i^{(0)}} \right) dt,
\end{aligned}$$

$$\frac{d}{dt} (u_i^\dagger, u_i^{(0)}) = 0.$$

Auxiliary problem:

$$\frac{\partial u_i^{\dagger(k)}}{\partial x_i} = 0; \quad -Re \left[\frac{\partial u_i^{\dagger(k)}}{\partial t} + u_j^{(0)} \frac{\partial u_i^{\dagger(k)}}{\partial x_j} \right] = -\frac{\partial p^{\dagger(k)}}{\partial x_i} + \frac{\partial^2 u_i^{\dagger(k)}}{\partial x_j^2} + \delta_{ki}$$

The resulting macroscopic equation is:

$$\int_0^T \langle u_k^{(0)} \rangle dt = - \int_0^T \mathcal{K}_{ki}^{eff} \left[\frac{\partial p^{(0)}}{\partial X_i} - \cancel{f_i^{(0)}} \right] dt,$$

with

$$\mathcal{K}_{ki}^{eff} = \langle u_i^{\dagger(k)} \rangle.$$

Auxiliary problem:

$$\frac{\partial u_i^{\dagger(k)}}{\partial x_i} = 0; \quad -Re \left[\frac{\partial u_i^{\dagger(k)}}{\partial t} + u_j^{(0)} \frac{\partial u_i^{\dagger(k)}}{\partial x_j} \right] = -\frac{\partial p^{\dagger(k)}}{\partial x_i} + \frac{\partial^2 u_i^{\dagger(k)}}{\partial x_j^2} + \delta_{ki}$$

equivalent to:

$$\frac{\partial \mathcal{A}_{ki}^{\dagger}}{\partial x_i} = 0,$$
$$-\rho \left[\frac{\partial \mathcal{A}_{ki}^{\dagger}}{\partial t} + u_j^{(0)} \frac{\partial \mathcal{A}_{ki}^{\dagger}}{\partial x_j} \right] = -\frac{\partial p_k^{\dagger}}{\partial x_i} + \mu \frac{\partial^2 \mathcal{A}_{ki}^{\dagger}}{\partial x_j^2} + \delta_{ki}.$$

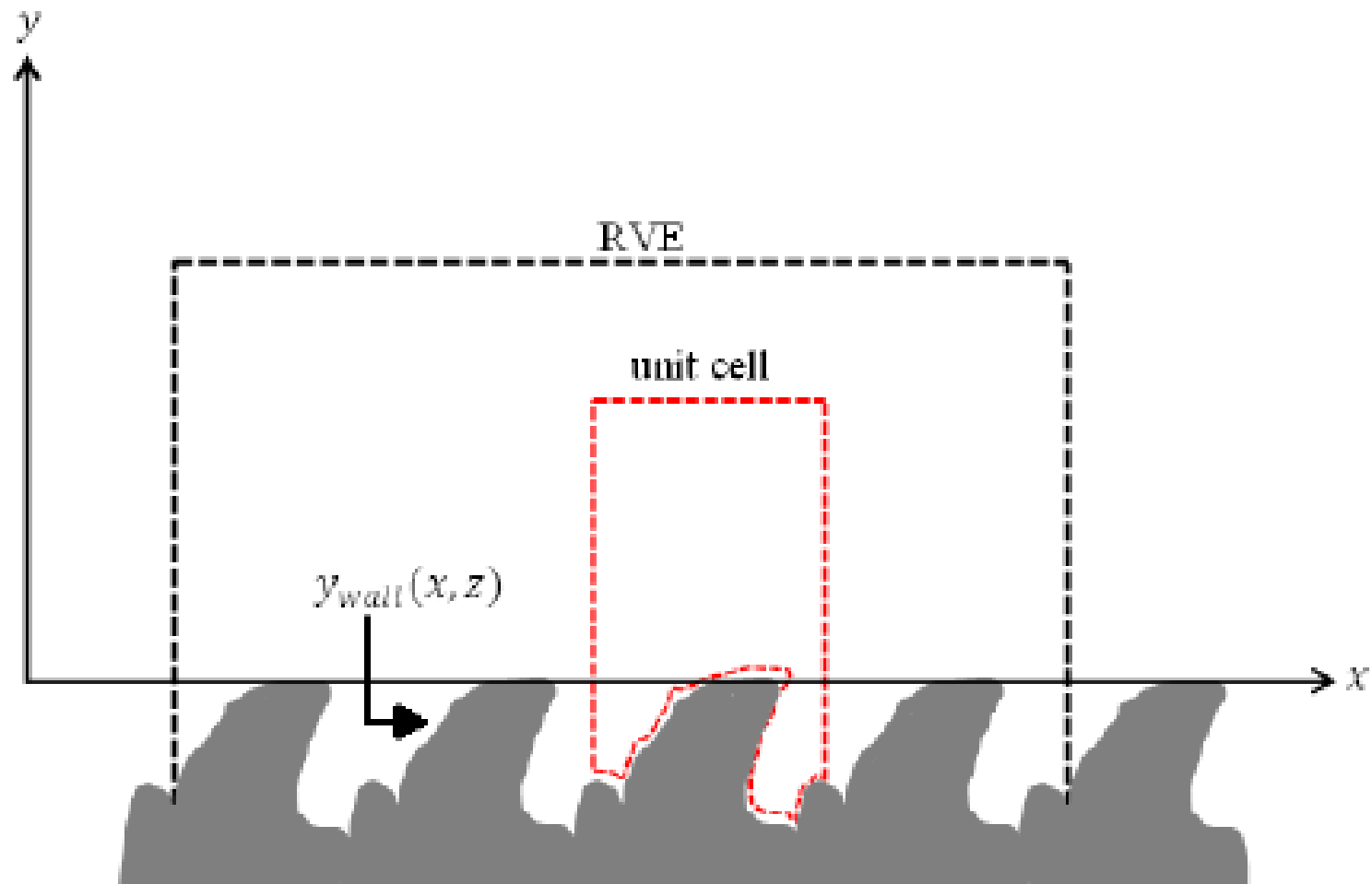
Same result as Whitaker's for the steady case:

$$\frac{\partial E_{ik}}{\partial x_i} = 0, \quad Re u_j^{(0)} \frac{\partial E_{ik}}{\partial x_j} = -\frac{\partial e_k}{\partial x_i} + \frac{\partial^2 E_{ik}}{\partial x_j^2} + \delta_{ik}$$

$$\mathcal{K}_{ik}^{eff} = \langle E_{ik} \rangle.$$

Same result as Lasseux et al. (JFM 2019) for the case of unsteady flows in porous media.

2. Flow over rough surfaces



$$\left\{ \begin{array}{l} \frac{\partial u_i}{\partial x_i} = 0, \\ \mathcal{R} \left[\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} \right] = -\frac{\partial p}{\partial x_i} + \frac{\partial^2 u_i}{\partial x_j^2}, \quad \mathcal{R} = \mathcal{U}l/\nu \end{array} \right.$$

Lagrange-Green identity: $0 = \int_0^T \left(p^{(0)}, \frac{\partial u_i^\dagger}{\partial x_i} \right) + \left(u_i^{(0)}, \left[\mathcal{R} \left(\frac{\partial u_i^\dagger}{\partial t} + u_j^{(0)} \frac{\partial u_i^\dagger}{\partial x_j} \right) - \frac{\partial p^\dagger}{\partial x_i} + \frac{\partial^2 u_i^\dagger}{\partial x_j^2} \right] \right) dt + \text{b.t.}$

+ no-slip conditions for u_i^\dagger at $y = y_{wall}$ and periodicity

$$\left\{ \begin{array}{l} \frac{\partial u_i^\dagger}{\partial x_i} = 0, \\ -\mathcal{R} \left(\frac{\partial u_i^\dagger}{\partial t} + u_j^{(0)} \frac{\partial u_i^\dagger}{\partial x_j} \right) = -\frac{\partial p^\dagger}{\partial x_i} + \frac{\partial^2 u_i^\dagger}{\partial x_j^2}, \end{array} \right.$$

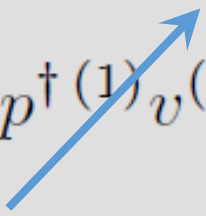
$$\text{b.t.} = \int_{\Omega} -\mathcal{R} v^{(0)} u_i^{(0)} u_i^\dagger - p^{(0)} v^\dagger + v^{(0)} p^\dagger + u_i^\dagger \frac{\partial u_i^{(0)}}{\partial y} - u_i^{(0)} \frac{\partial u_i^\dagger}{\partial y} dx dz = 0$$

at $y \rightarrow +\infty$

Choice for the adjoint
boundary conditions at
the outer edge of the RVE:

$$\frac{\partial u_i^{\dagger(k)}}{\partial y} = \delta_{ik}, \quad v^{\dagger(k)} := u_2^{\dagger(k)} = 0 \quad \text{at } y \rightarrow +\infty$$

$$[a] = \frac{1}{\Omega} \int_{\Omega_f} a \, dx \, dz.$$

$$\begin{aligned} \lim_{y \rightarrow +\infty} [u^{(0)}] &:= \lim_{y \rightarrow +\infty} [u_1^{(0)}] = \lim_{y \rightarrow +\infty} [u^{\dagger(1)} \left(\frac{\partial u^{(0)}}{\partial y} - \mathcal{R} u^{(0)} v^{(0)} \right)] + \\ &+ [w^{\dagger(1)} \left(\frac{\partial w^{(0)}}{\partial y} - \mathcal{R} v^{(0)} w^{(0)} \right)] + [p^{\dagger(1)} v^{(0)}]; \end{aligned}$$


and similarly for $\lim_{y \rightarrow +\infty} [w^{(0)}]$

First attempt:

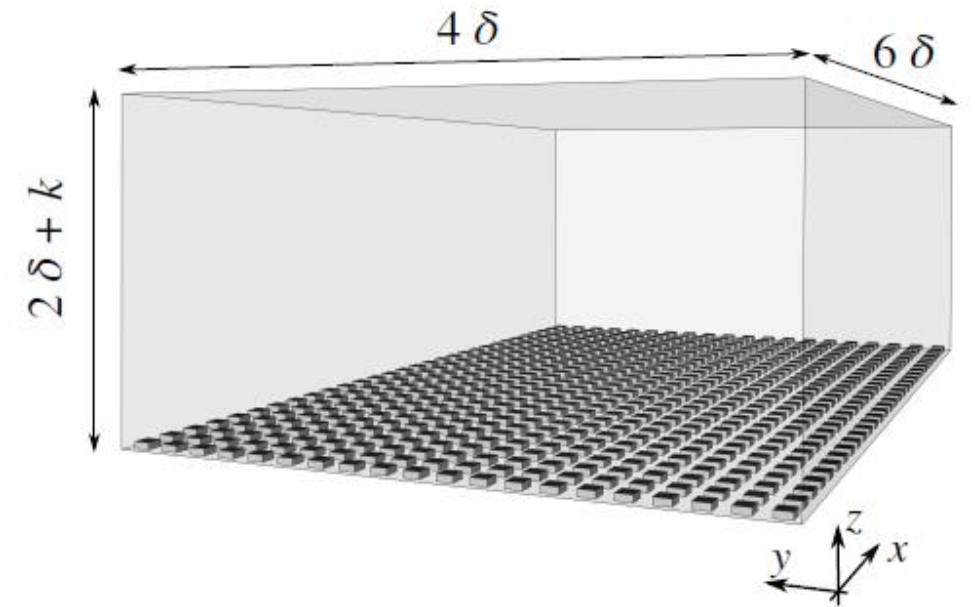
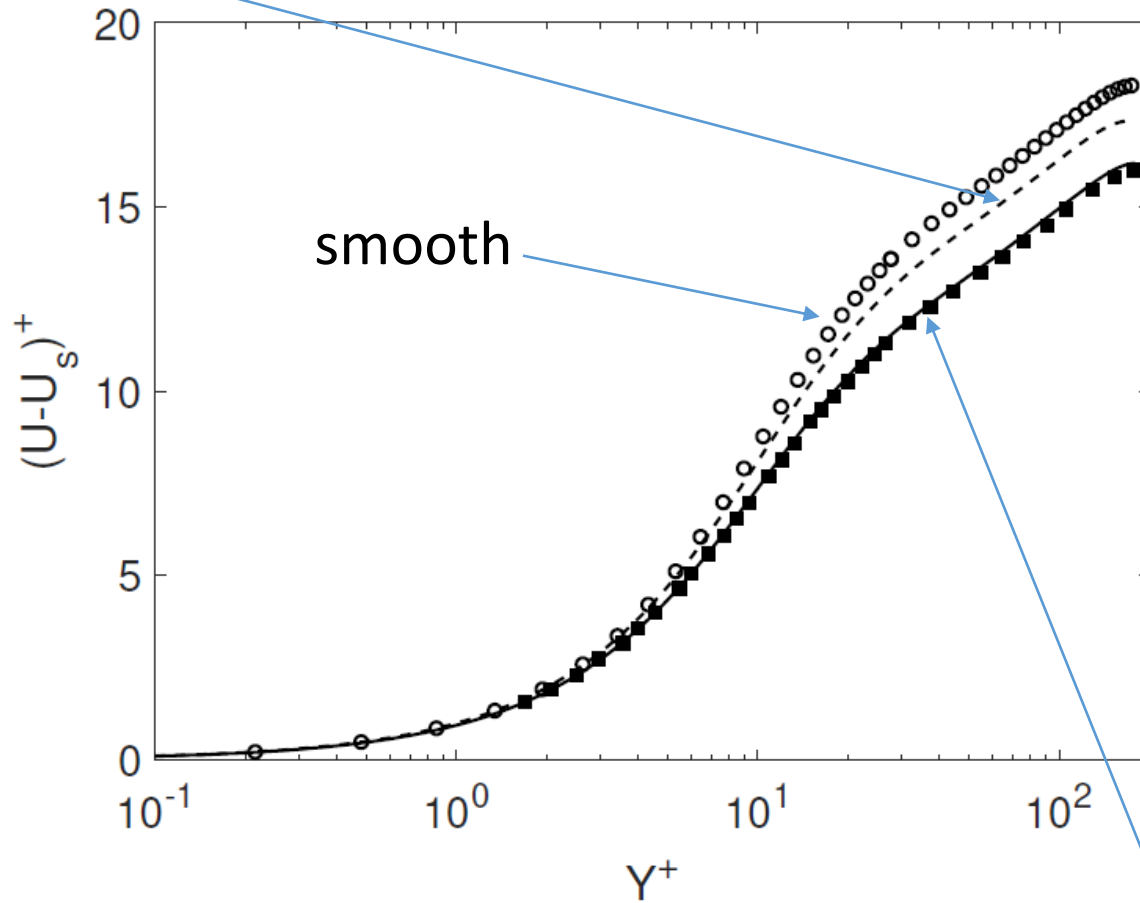
$$U|_{Y \rightarrow 0^+} = \epsilon [u^{(0)}]|_{y \rightarrow +\infty}, \quad V|_{Y \rightarrow 0^+} = 0, \quad W|_{Y \rightarrow 0^+} = \epsilon [w^{(0)}]|_{y \rightarrow +\infty}$$

Flow in a channel, ***lower transitionally rough regime***: $\mathcal{R} \rightarrow 0$

$$\left\{ \begin{array}{l} \begin{pmatrix} U_s \\ W_s \end{pmatrix} = \epsilon \Lambda \frac{\partial}{\partial Y} \begin{pmatrix} U \\ W \end{pmatrix} \Big|_{Y=0} \\ V|_{Y=0} = 0 \end{array} \right.$$

$$\hat{\tau}_{lower\ wall}^{total} = \mu \left. \frac{\partial \hat{U}}{\partial \hat{Y}} \right|_{\hat{Y}=0} - \rho \overline{\hat{U}'\hat{V}'} \Big|_{\hat{Y}=0}$$

slip, no wall transpiration



DNS by Laci, Sudhakar & Bagheri (2018)

The transpiration velocity

$$\frac{\partial}{\partial Y} \begin{pmatrix} U \\ W \end{pmatrix} \Big|_{Y=0} = \epsilon^{-1} \mathbf{B} \begin{pmatrix} U_s \\ W_s \end{pmatrix} \quad \mathbf{B} = \mathbf{\Lambda}^{-1} \text{ of components } b_{jk}$$

Linearity shows that \mathbf{A} exists, such that: $\begin{pmatrix} u^{(0)} \\ w^{(0)} \end{pmatrix} = \mathbf{A} \frac{\partial}{\partial Y} \begin{pmatrix} U \\ W \end{pmatrix} \Big|_{Y=0}$

Then: $\begin{pmatrix} u^{(0)} \\ w^{(0)} \end{pmatrix} = \epsilon^{-1} \mathbf{A} \mathbf{B} \begin{pmatrix} U_s \\ W_s \end{pmatrix} \longrightarrow u_i^{(0)} = \epsilon^{-1} a_{ij} b_{jk} U_{k,s}$

The transpiration velocity

The dimensional continuity equation yields

$$\hat{V} \Big|_{\hat{Y}=0} = - \int_{\hat{Y}_{wall}}^0 \left(\frac{\partial \hat{U}}{\partial \hat{X}} + \frac{\partial \hat{W}}{\partial \hat{Z}} \right) d\hat{Y} = - \frac{\partial}{\partial \hat{X}} \int_{\hat{Y}_{wall}}^0 \hat{U} d\hat{Y} - \frac{\partial}{\partial \hat{Z}} \int_{\hat{Y}_{wall}}^0 \hat{W} d\hat{Y}$$

normalize with microscopic scales:

$$v^{(0)} \Big|_{y=0} + \epsilon v^{(1)} \Big|_{y=0} = - \frac{\partial}{\partial x_i} \int_{y_{wall}}^0 u_i^{(0)} dy - \epsilon \left[\frac{\partial}{\partial x_i} \int_{y_{wall}}^0 u_i^{(1)} dy + \frac{\partial}{\partial X_i} \int_{y_{wall}}^0 u_i^{(0)} dy \right]$$

The transpiration velocity

$$v^{(0)}|_{y=0} = -\frac{\partial}{\partial x_i} \int_{y_{wall}}^0 u_i^{(0)} dy,$$

$$v^{(1)}|_{y=0} = -\frac{\partial}{\partial x_i} \int_{y_{wall}}^0 u_i^{(1)} dy - \frac{\partial}{\partial X_i} \int_{y_{wall}}^0 a_{ij} b_{jk} (U_{k,s}/\epsilon) dy.$$



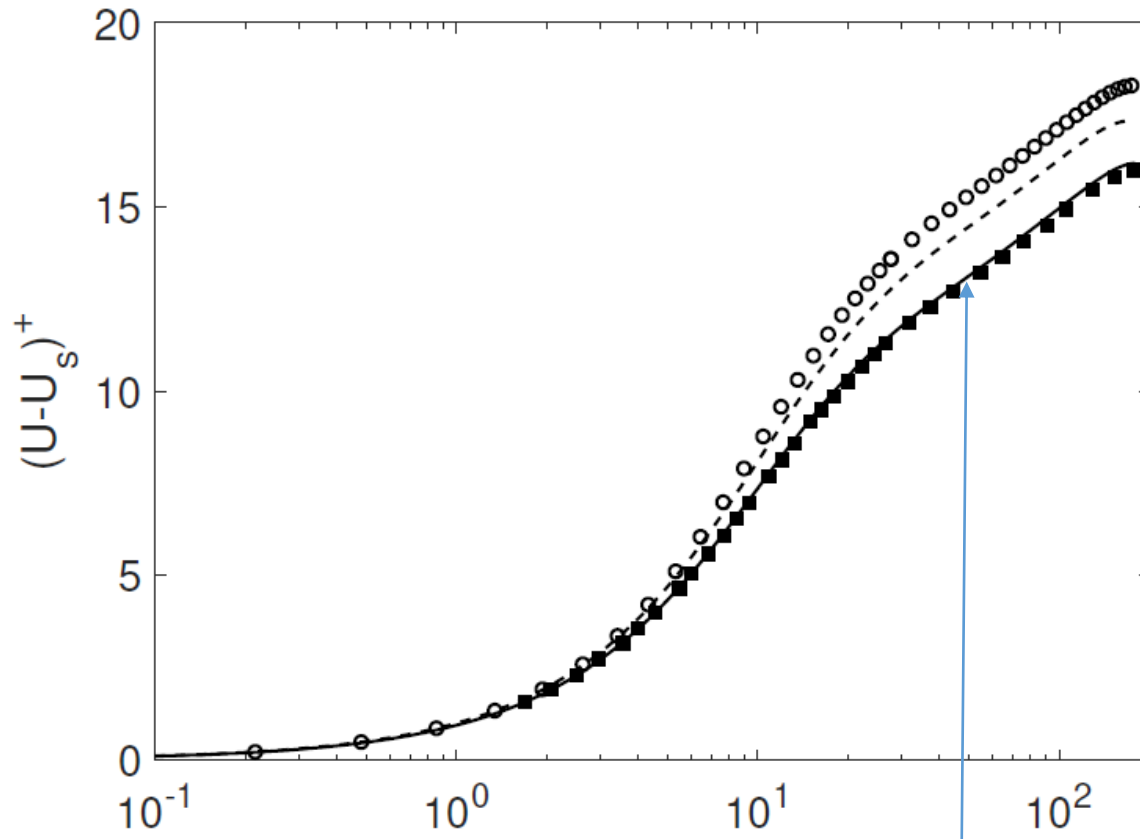
$$[v^{(0)}] = 0, \quad [v^{(1)}] = -\epsilon^{-1} \left[\int_{y_{wall}}^0 [a_{ij}] b_{jk} dy \right] \frac{\partial U_{k,s}}{\partial X_i}$$

The transpiration velocity

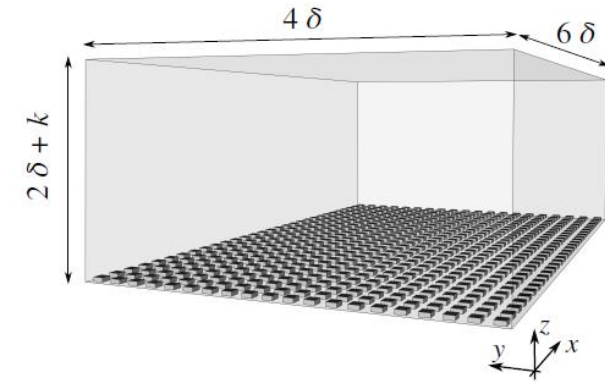
$$V|_{Y=0} = -\epsilon m_{ik} \frac{\partial U_{k,s}}{\partial X_i} = -\epsilon \left[m_{11} \frac{\partial U_s}{\partial X} + m_{13} \frac{\partial W_s}{\partial X} + m_{31} \frac{\partial U_s}{\partial Z} + m_{33} \frac{\partial W_s}{\partial Z} \right]$$

$$m_{ik} = \left[\int_{y_{wall}}^0 [a_{ij}] dy \right] b_{jk}$$

$$\hat{\tau}_{lower\ wall}^{total} = \mu \left. \frac{\partial \hat{U}}{\partial \hat{Y}} \right|_{\hat{Y}=0} - \rho \overline{\hat{U}'\hat{V}'} \Big|_{\hat{Y}=0}$$



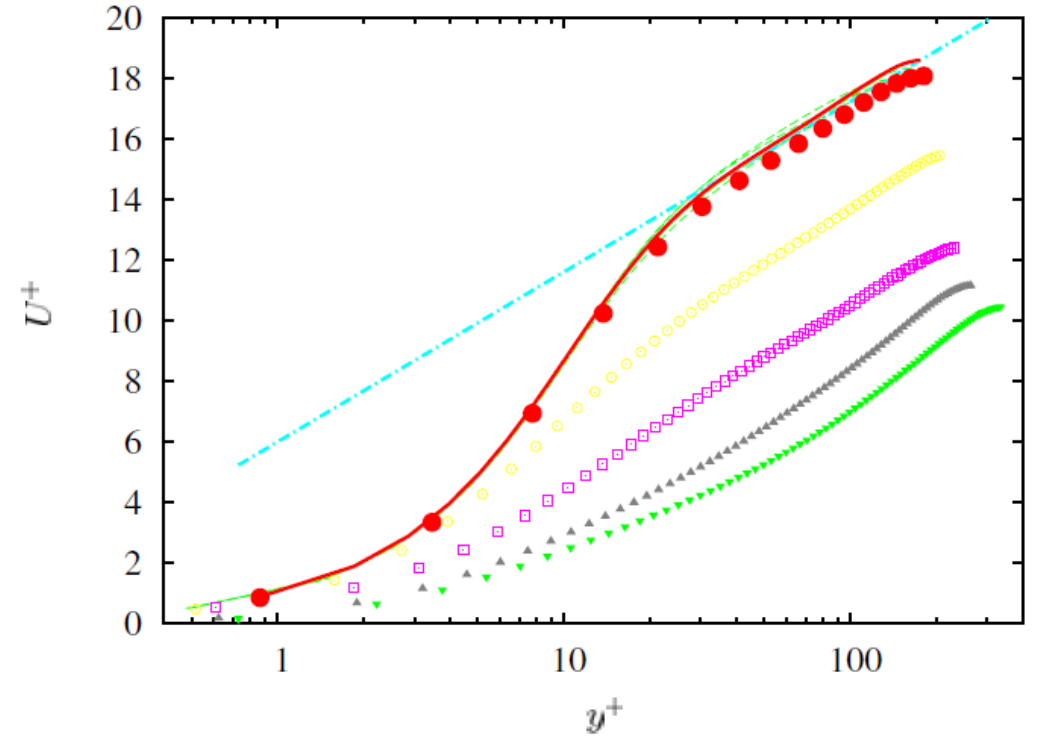
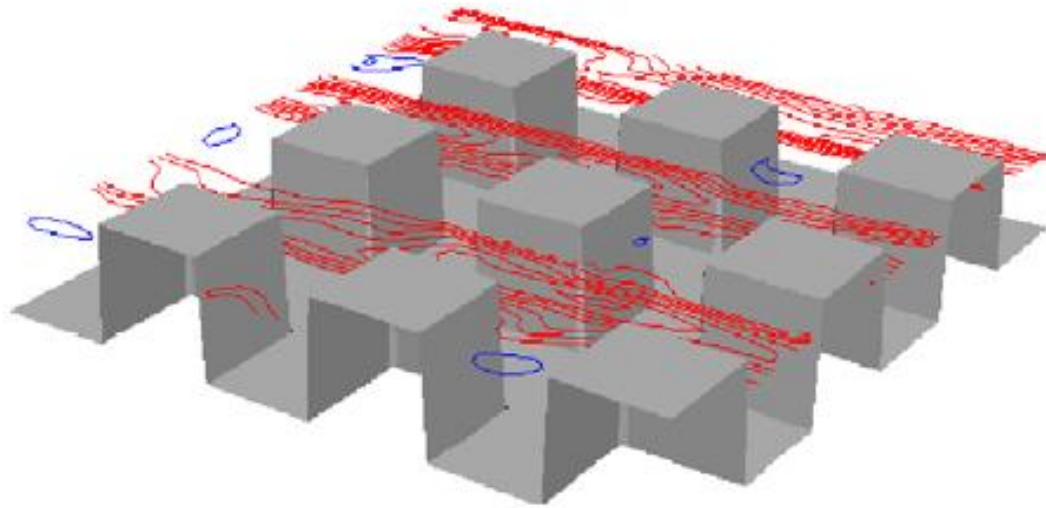
Y^+ perfect agreement between the model and the feature-resolving DNS, in the lower transitionally rough regime



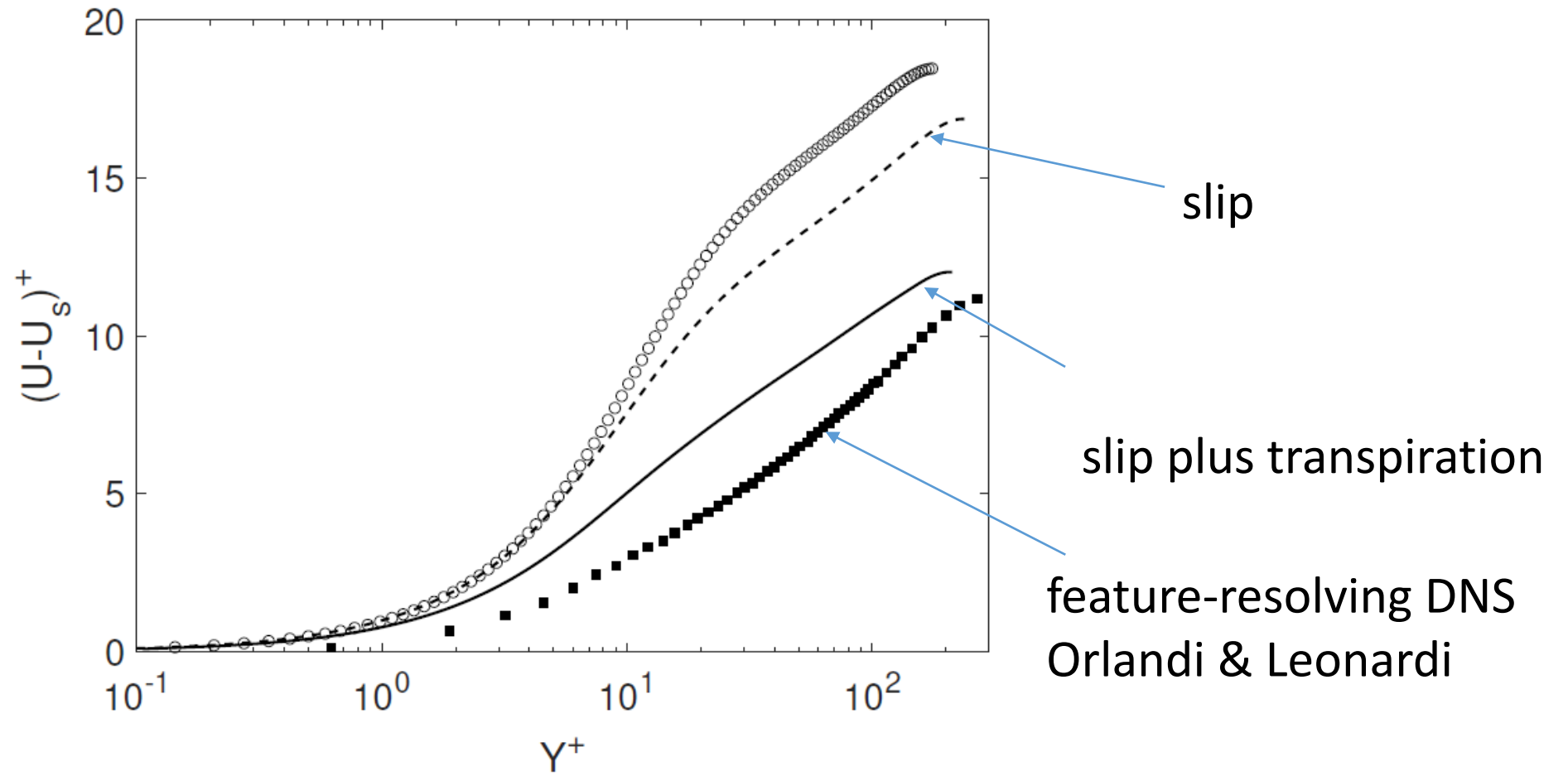
$$V \Big|_{Y=0} = -\epsilon m_{11} \left[\frac{\partial U}{\partial X} + \frac{\partial W}{\partial Z} \right] \Big|_{Y=0}$$

$$V \Big|_{Y=0} = \epsilon m_{11} \frac{\partial V}{\partial Y} \Big|_{Y=0}$$

Upper transitionally rough regime



Orlandi & Leonardi (2006)



PERSPECTIVES

1. Can treat unsteady and turbulent flows in **porous media**
2. Can treat flow past **rough walls** (and interfaces, for example between a clear fluid region and a porous layer)



we can now parametrize any (sufficiently regular) rough wall with Λ and \mathbf{M} and use such tensors to correlate the roughness pattern and amplitude to the *roughness function*.

This opens further perspectives for wall-control and optimization purposes, also using deformable, surface-based micro-actuators.

