• Let us solve the general transport equation in the following domain,





Note: All dimensions are in the SI system (MKS).

• With the given boundary conditions, initial conditions, and physical properties, the general transport equation,



Reduces to the following governing equation,

$$\frac{\partial \phi}{\partial x} = 1$$

• That has the following analytical solution,

$$\phi_x = x$$





- In this example, the quantity of interest (QoI) is a bounded quantity.
- In this case, the QoI cannot be larger than one (the analytical solution).
- Large URFs have fast convergence rate but the solution might become unbounded or oscillatory.
- Instead, if we use low URFs, the solution is very stable (bounded and non-oscillatory).
- However, the convergence rate is very slow.
- A tolerance in the order of 0.01 is just a pretty picture.
- Acceptable accuracy can be obtained with a tolerance level in the order of 0.001 and lower.
- In general, to increase the accuracy we need to use low tolerances.
- Choosing URF is a compromise between accuracy, convergence rate, and stability.
- In some cases, if you use large URF (more than 0.7), the solution becomes a little bit oscillatory or unbounded.
- Unbounded solutions are not desirable in CFD.



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URF 0.5 Tolerance 0.001 www.wolfdynamics.com/training/OF_WS2020/figs/f7.gif



URF 0.5 Tolerance 0.01 www.wolfdynamics.com/training/OF_WS2020/figs/f6.gif



URF 0.7 Tolerance 0.0001 www.wolfdynamics.com/training/OF_WS2020/figs/f8.gif